Subhi Alsous:

* Performed extra research on the control theory by looking closely to the characteristics and differences between the proportional controller, PI and PID.
* Examined the results and graphs of the TCRT5000 sensor in order to find a way to apply the control algorithm accordingly.
* Viewed a couple of code segments regarding the implementation of PI and PID controllers
* Prepared notes for me to refer to during the process of control implementation.